

Master Degree in ICT
for Internet and
Multimedia

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Academic Year
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Curriculum and Contrastive Learning in LiDAR Semantic Segmentation

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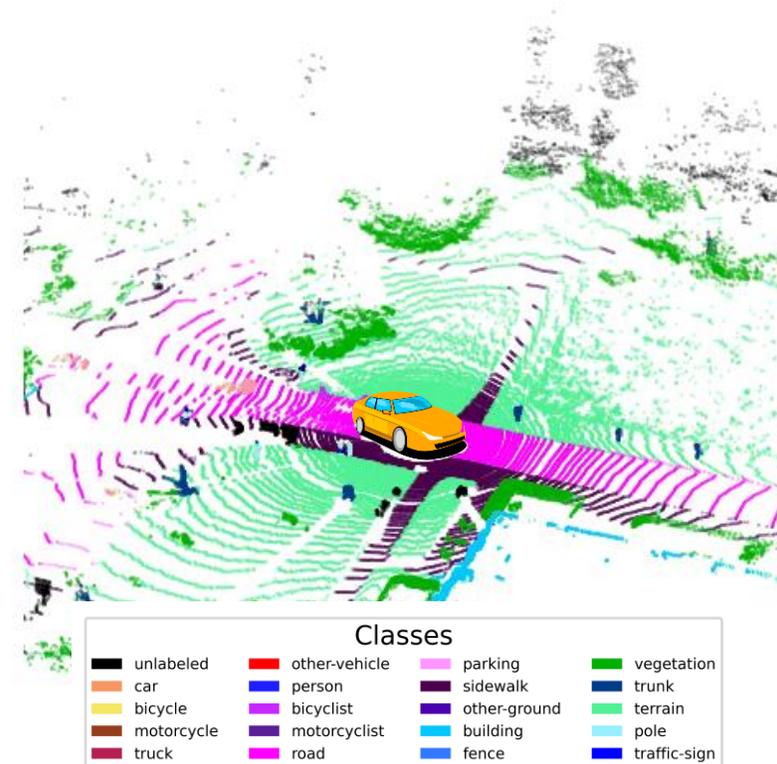
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Umberto Michieli

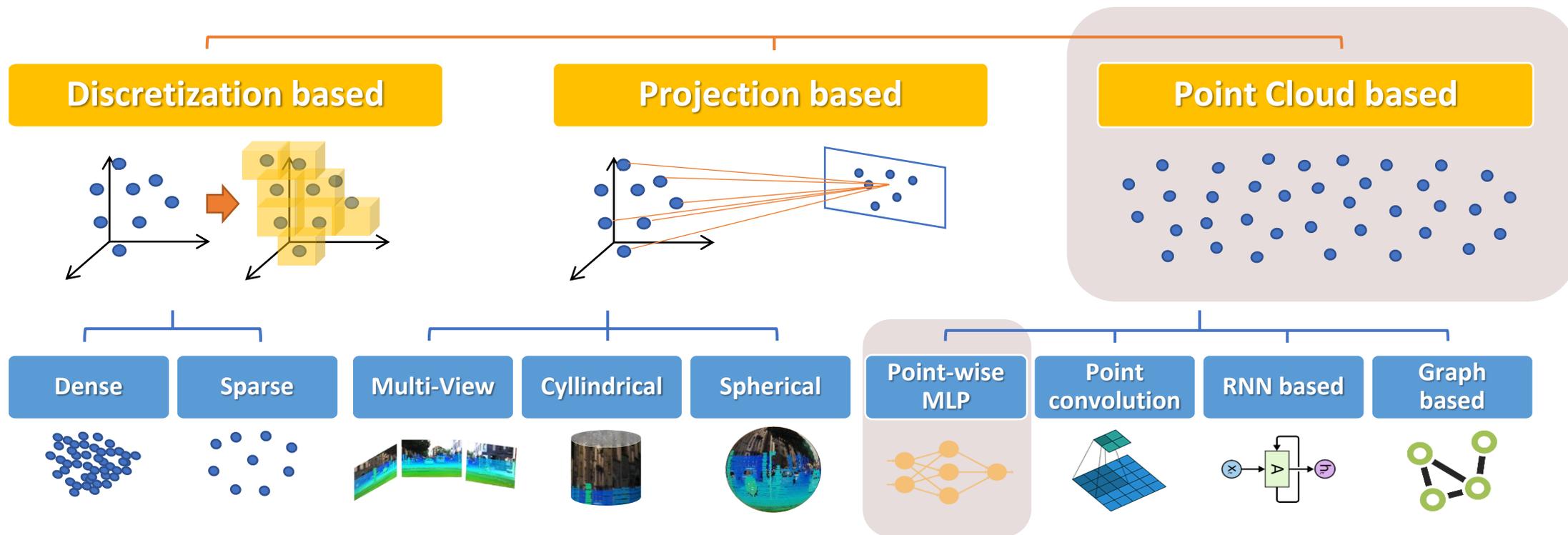


LiDAR Semantic Segmentation

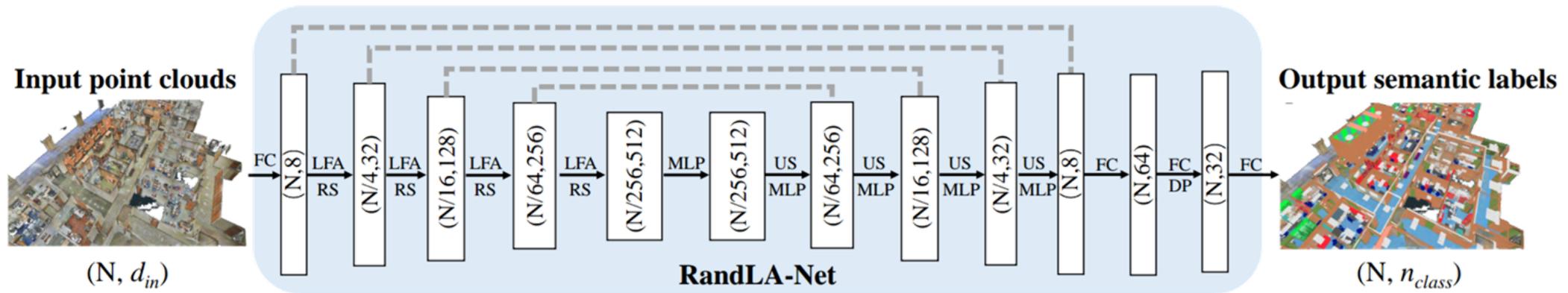
- **Classification of 3D points** for scene understanding.
- Many **applications**, e.g., autonomous driving, robotics, remote sensing.
 - > SemanticKITTI dataset [1]
- **Deep Learning** methods.
 - > RandLA-Net [2]



LiDAR SS methods taxonomy



Deep Learning architecture



Standard training



Output



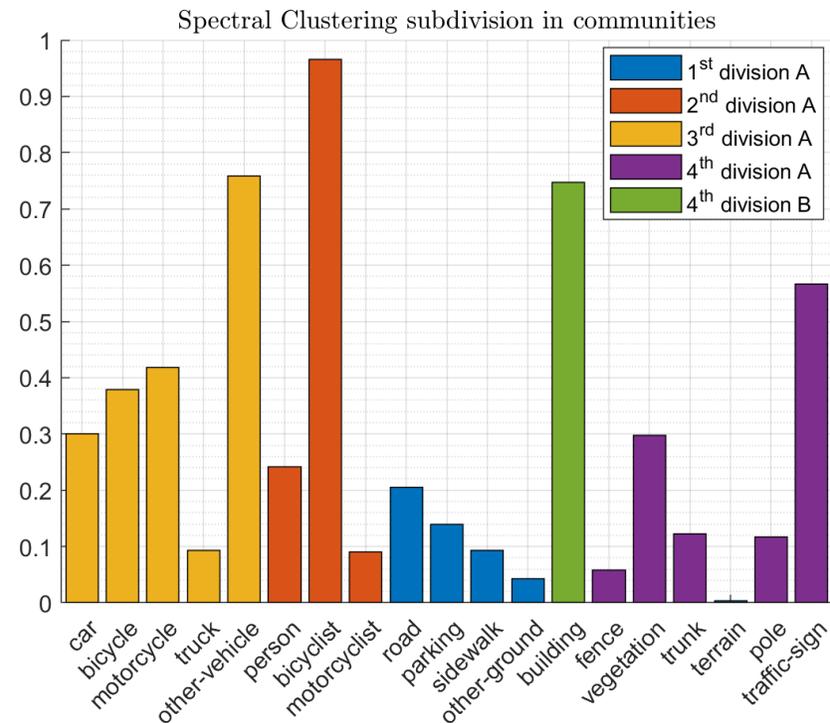
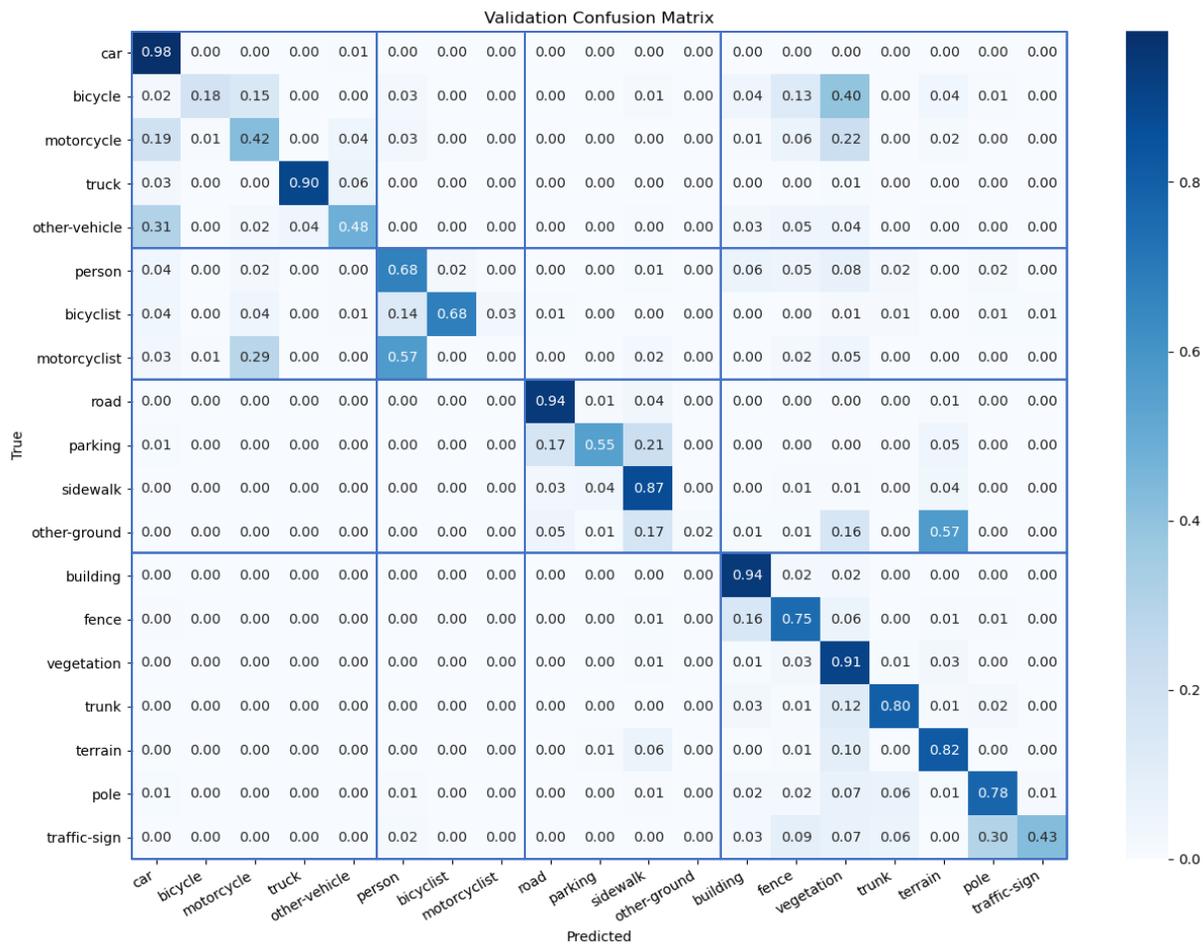
Dataset



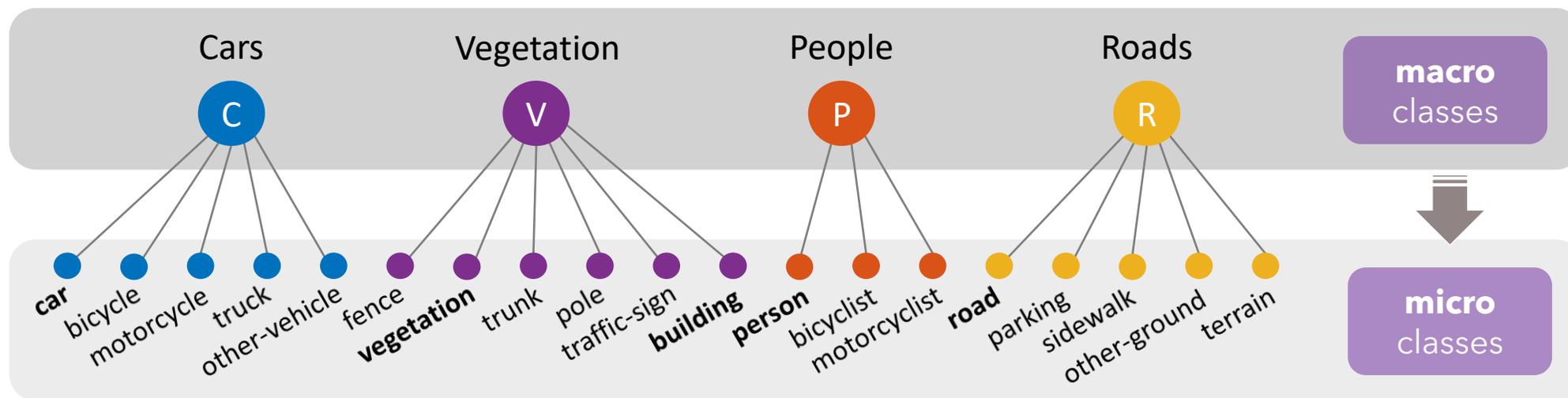
Learning methods

Analyses

Output and dataset analyses

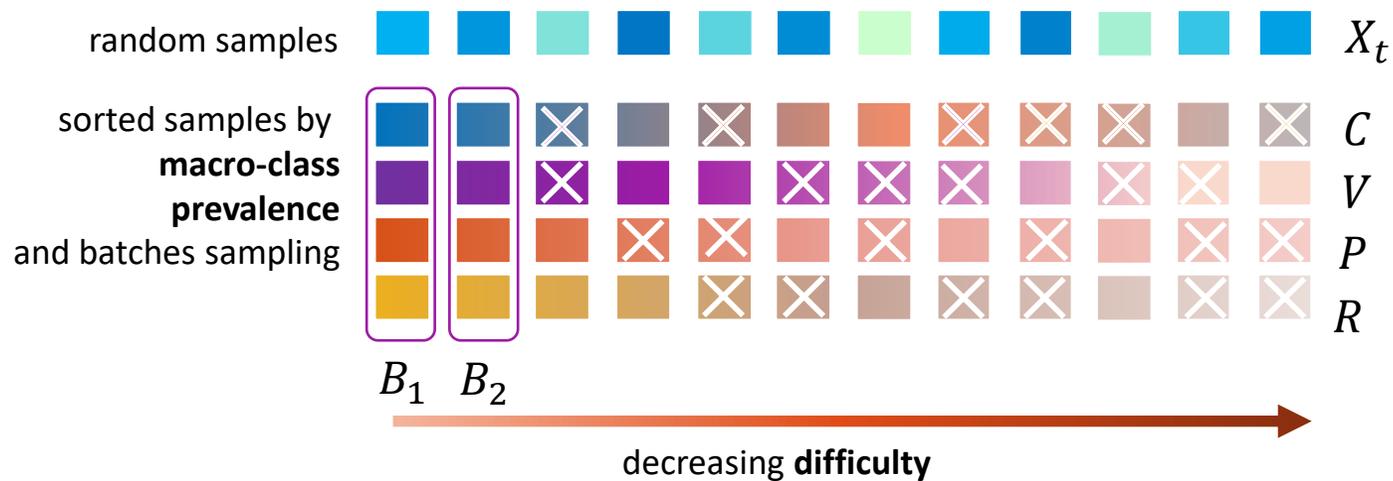
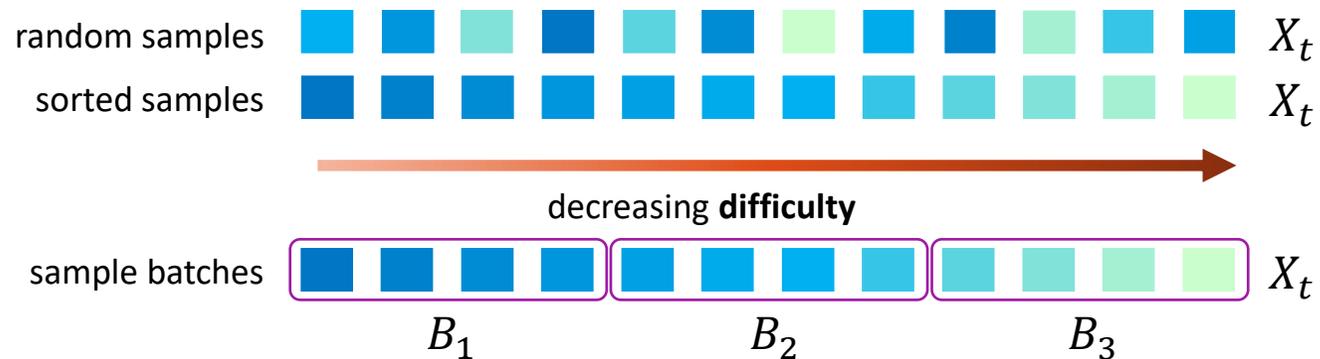
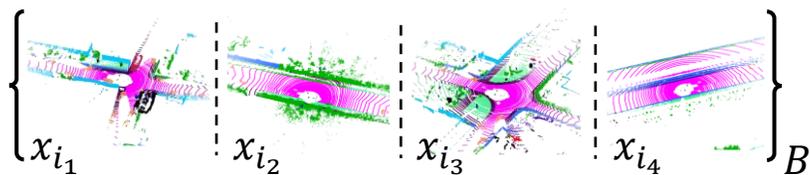


Hierarchical Grouping



Hierarchical loss function: $\mathcal{L}_{hierarchy} = \mathcal{L}_{micro} + \gamma \cdot \mathcal{L}_{macro}$

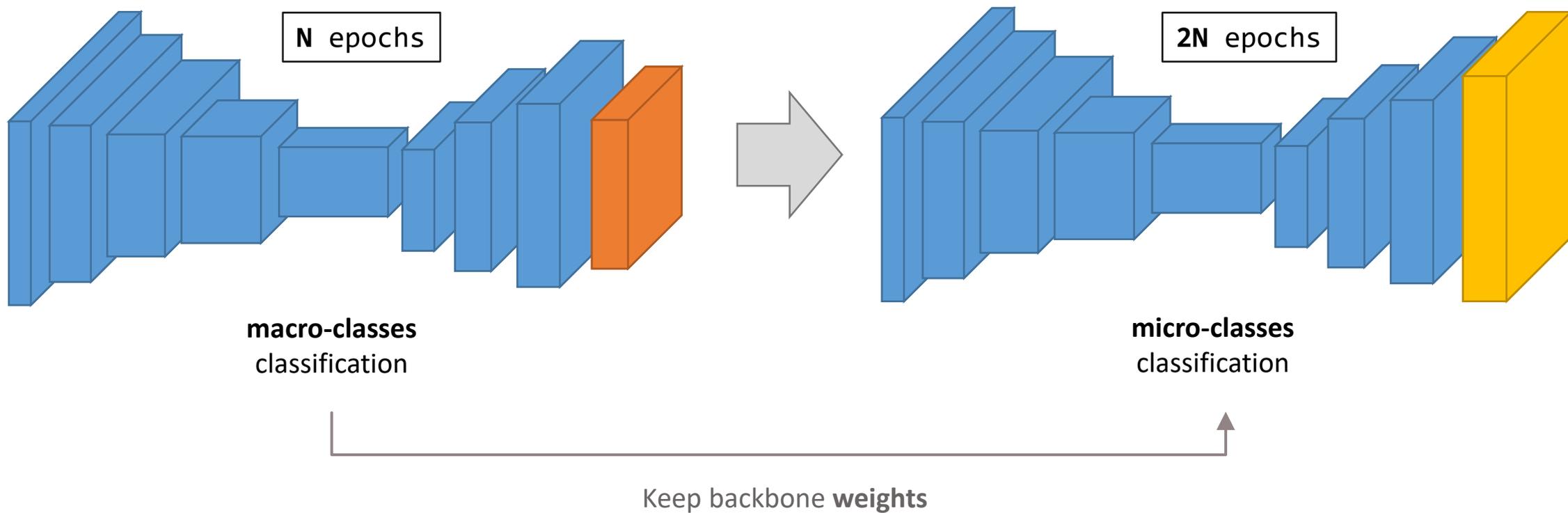
Batch Organization



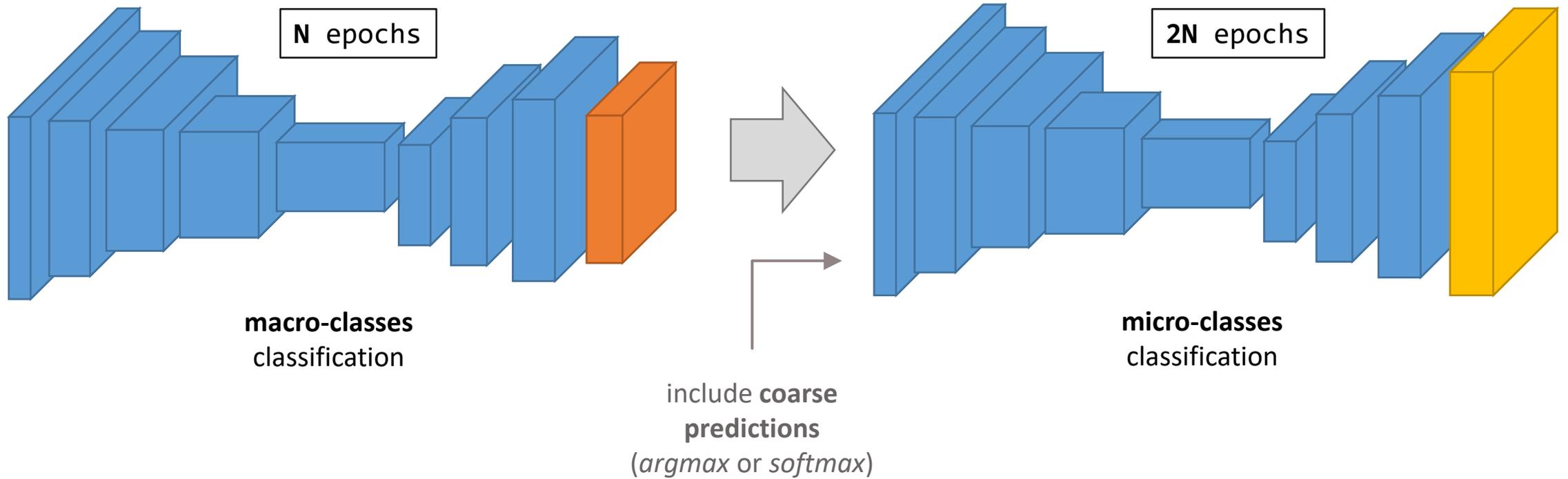
Ordering criteria:

- mIoU
- number of points

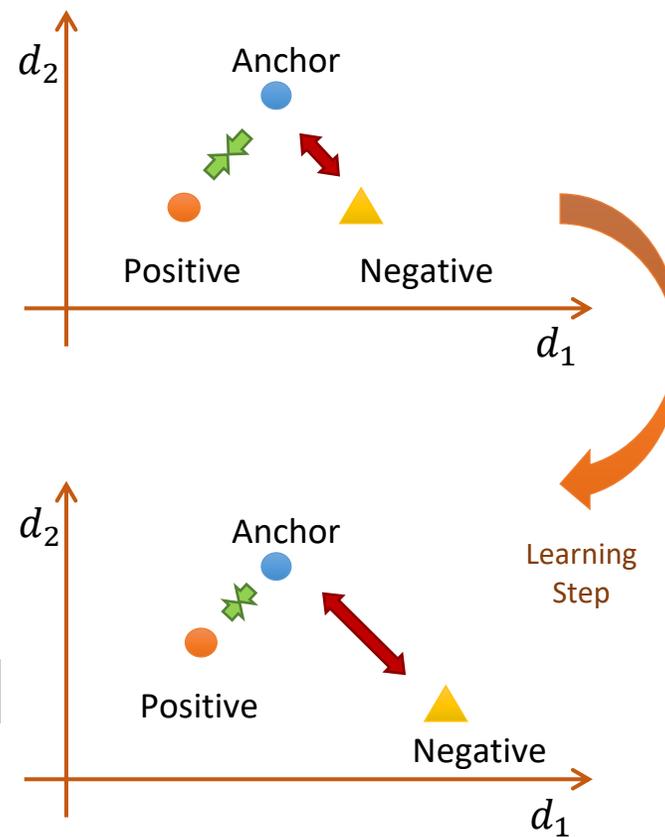
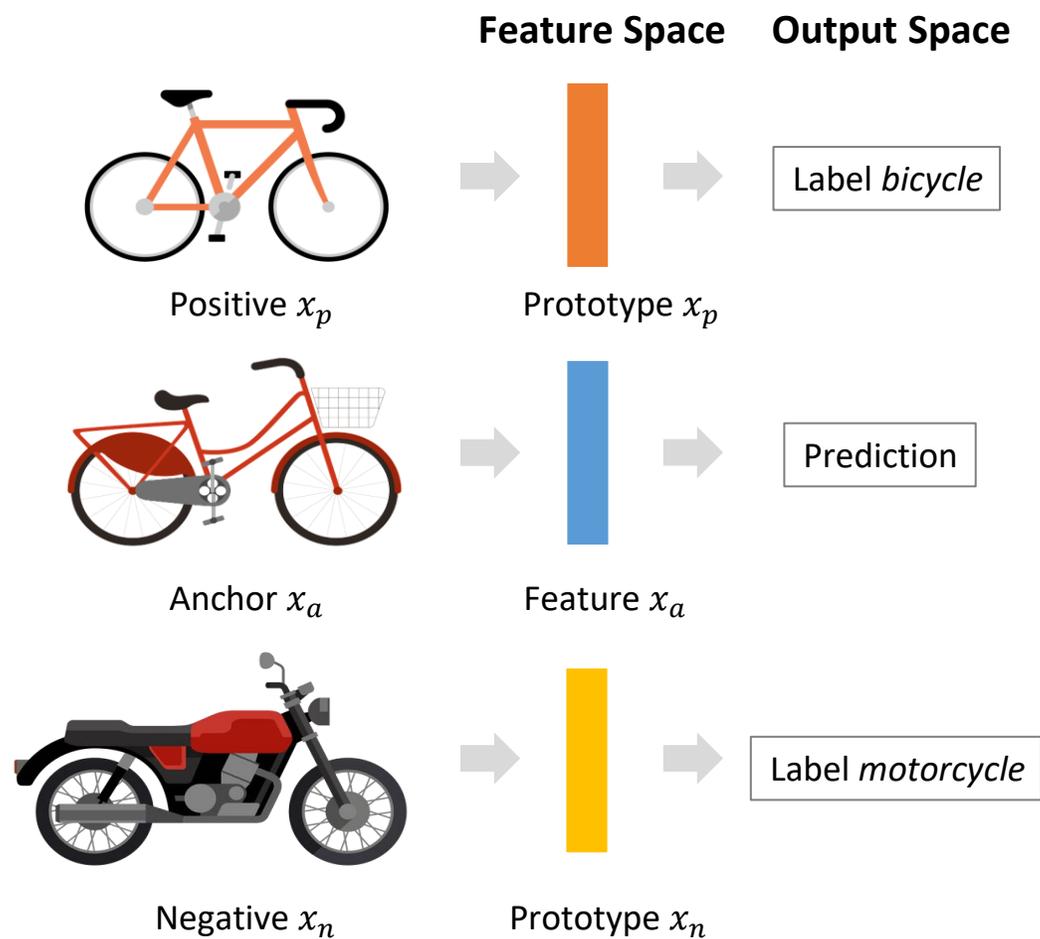
Coarse-to-Fine training



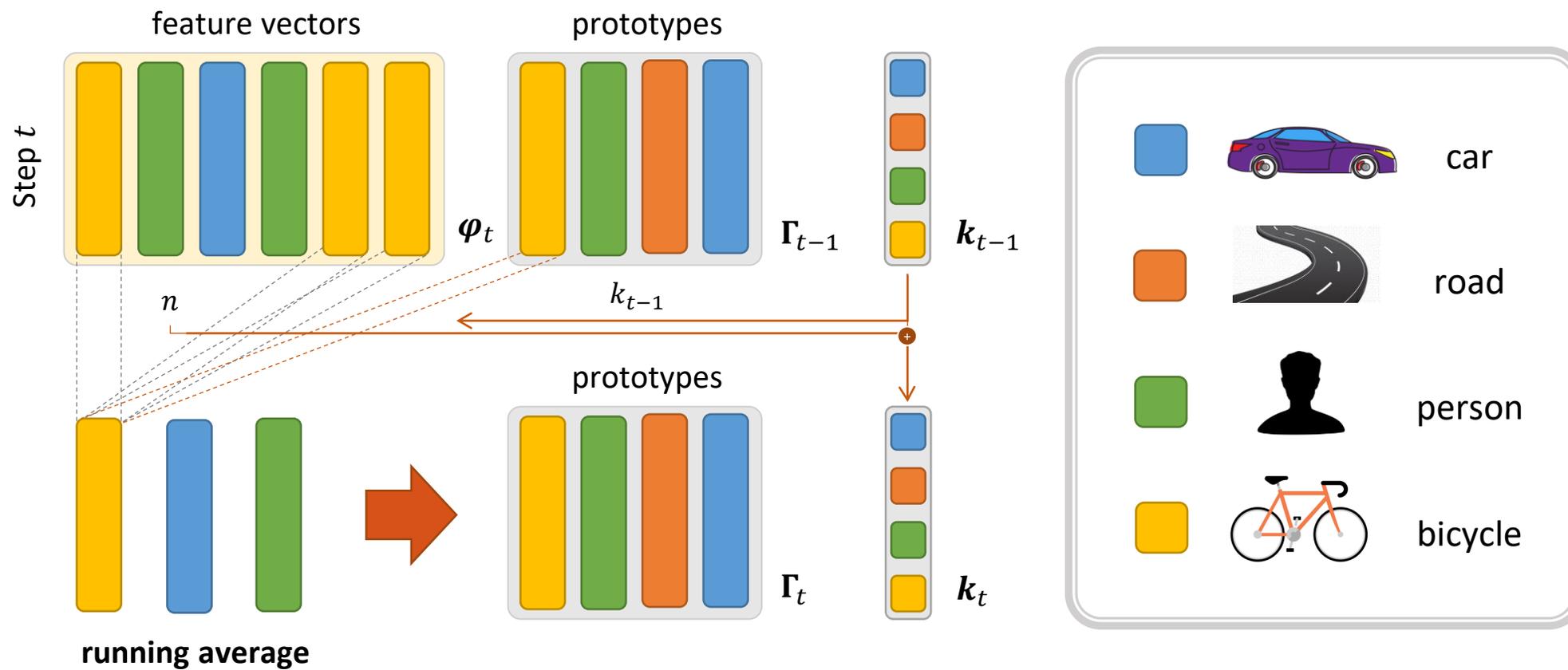
Coarse-to-Fine training



Contrastive Learning



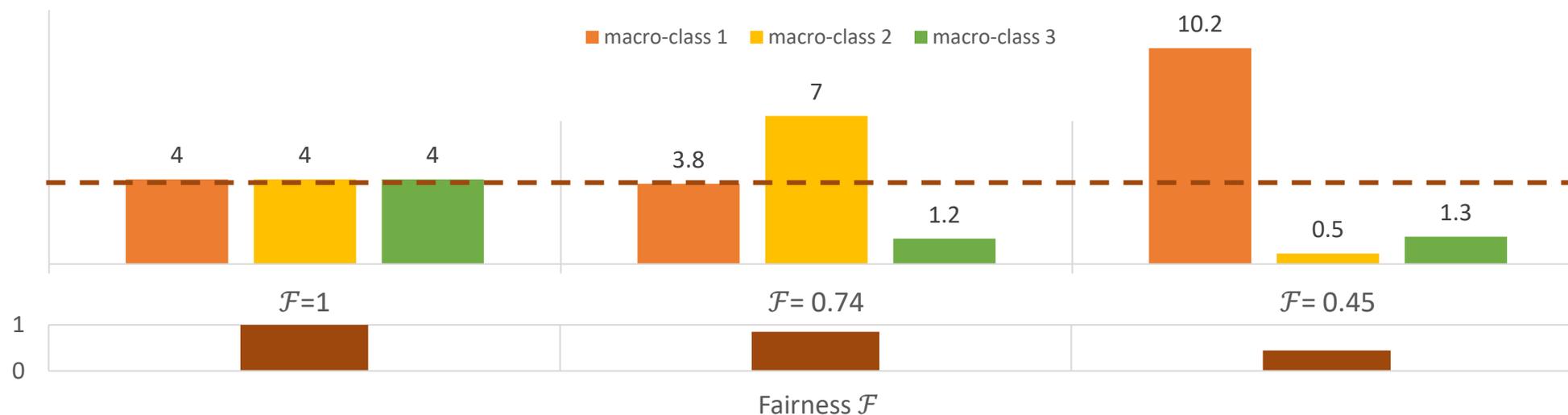
Feature Level



Jain's fairness index

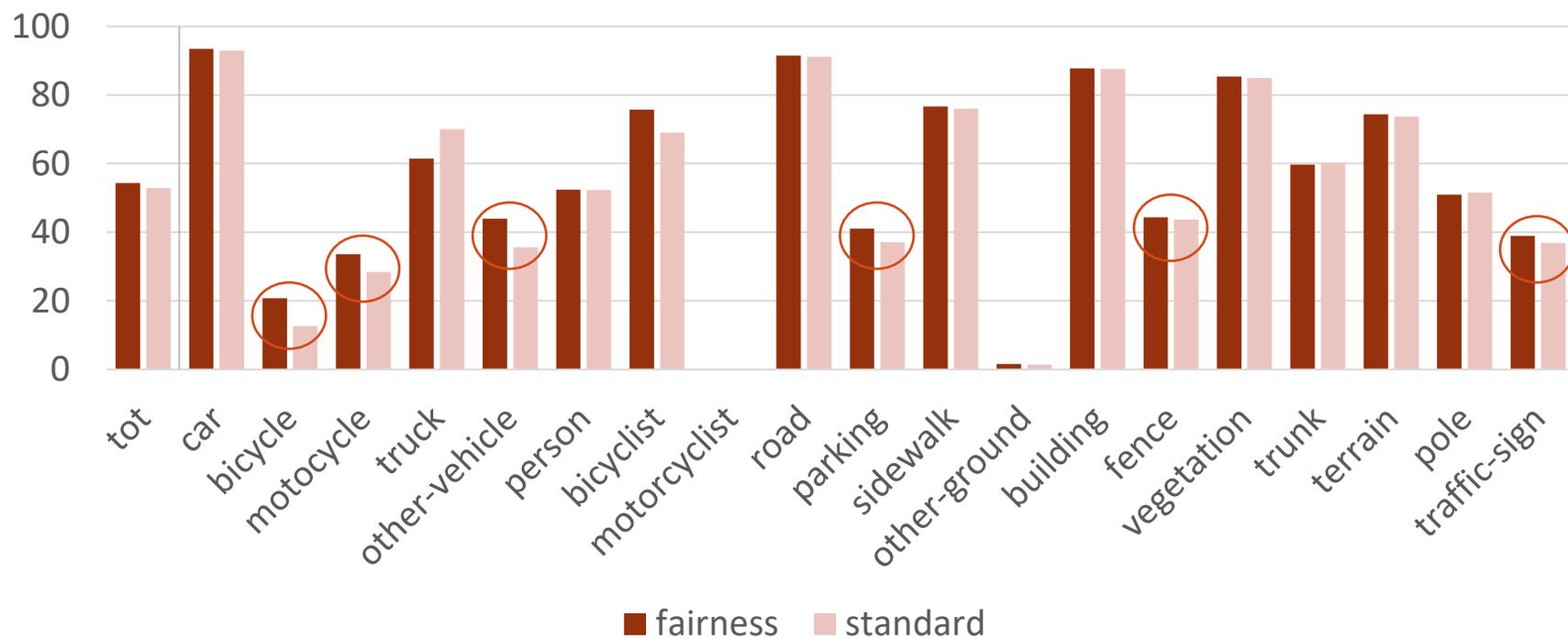
Fairness index:
$$\mathcal{F} = \sum_{k=1}^M \mathcal{F}_k, \quad \mathcal{F}_k = \frac{(\sum_{i=1}^n p_i)^2}{n \cdot \sum_{i=1}^n p_i^2}$$

Fairness loss function:
$$\mathcal{L}_{\mathcal{F}} = \mathcal{L}_{micro} + \gamma \cdot (1 - \mathcal{F})$$

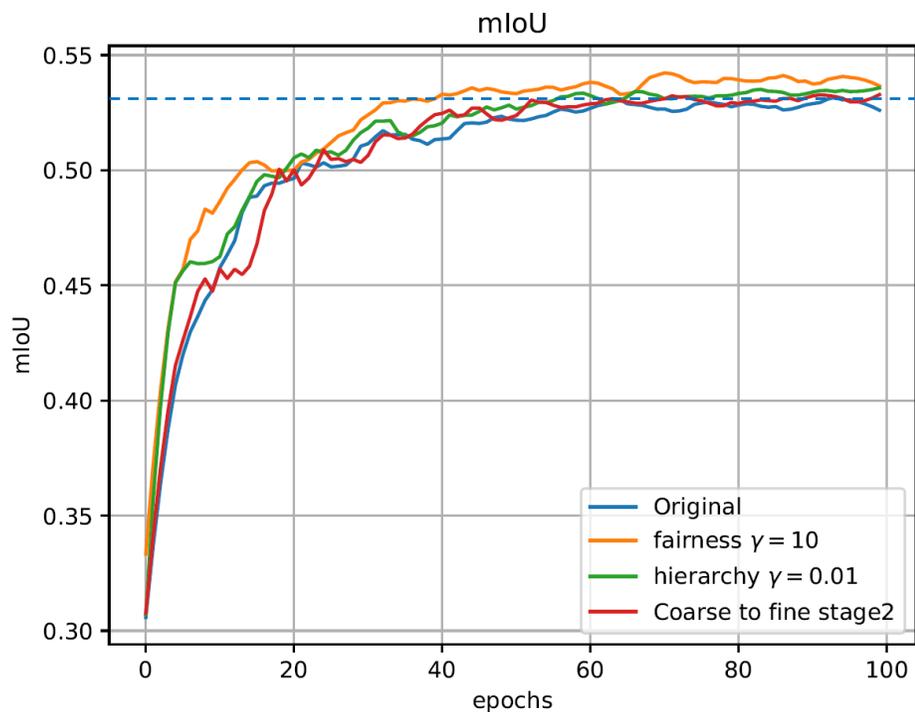


Quantitative Results

Per class mIoU - fairness tests



Additional Results



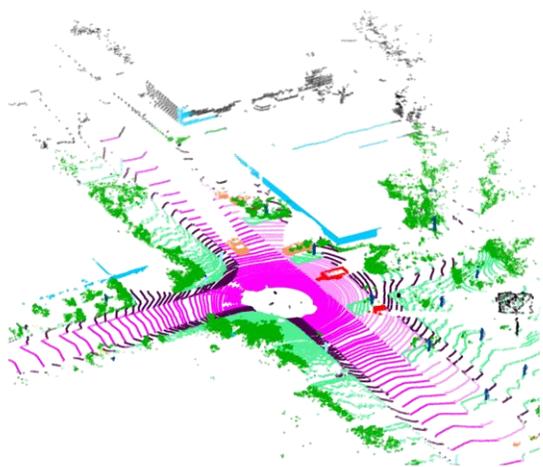
Tests with original batch size
 $b = 6$



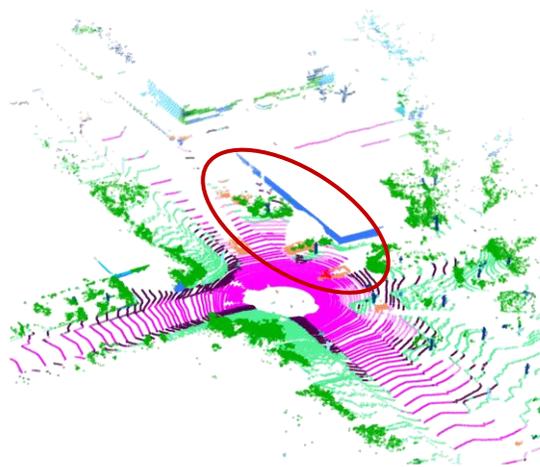
Trial name	accuracy	mIoU
Original	89.25	52.91
fairness $\gamma = 10$ + C2F	87.96	53.00
hierarchy $\gamma = 0.01$ + fairness $\gamma = 10$	89.86	53.87
hierarchy $\gamma = 0.01$ + C2F	89.60	52.95
hierarchy $\gamma = 0.05$ + fairness $\gamma = 10$	89.56	53.99
hierarchy $\gamma = 0.05$ + C2F	89.53	54.12
hierarchy $\gamma = 0.05$ + fairness $\gamma = 10$ + C2F	89.69	54.34

Ablation Study

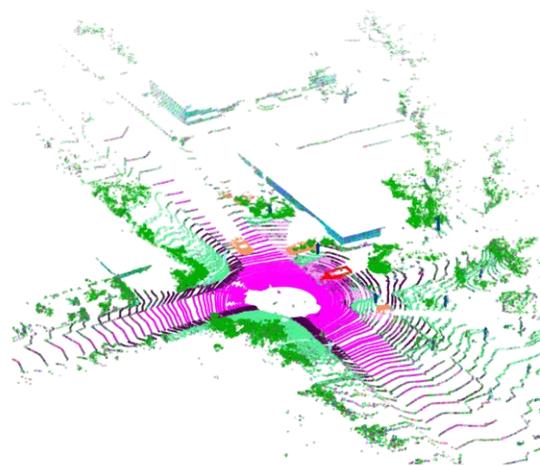
Qualitative Results



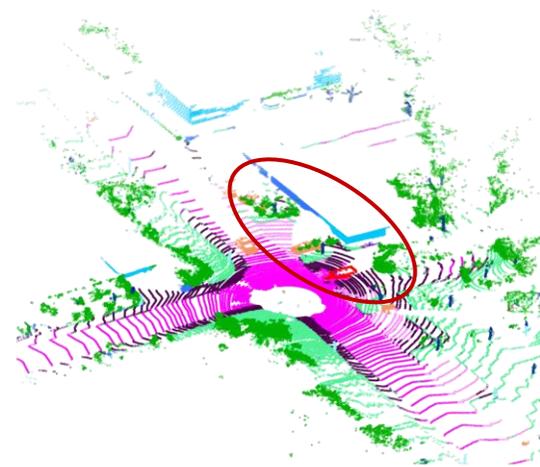
Groundtruth



Standard



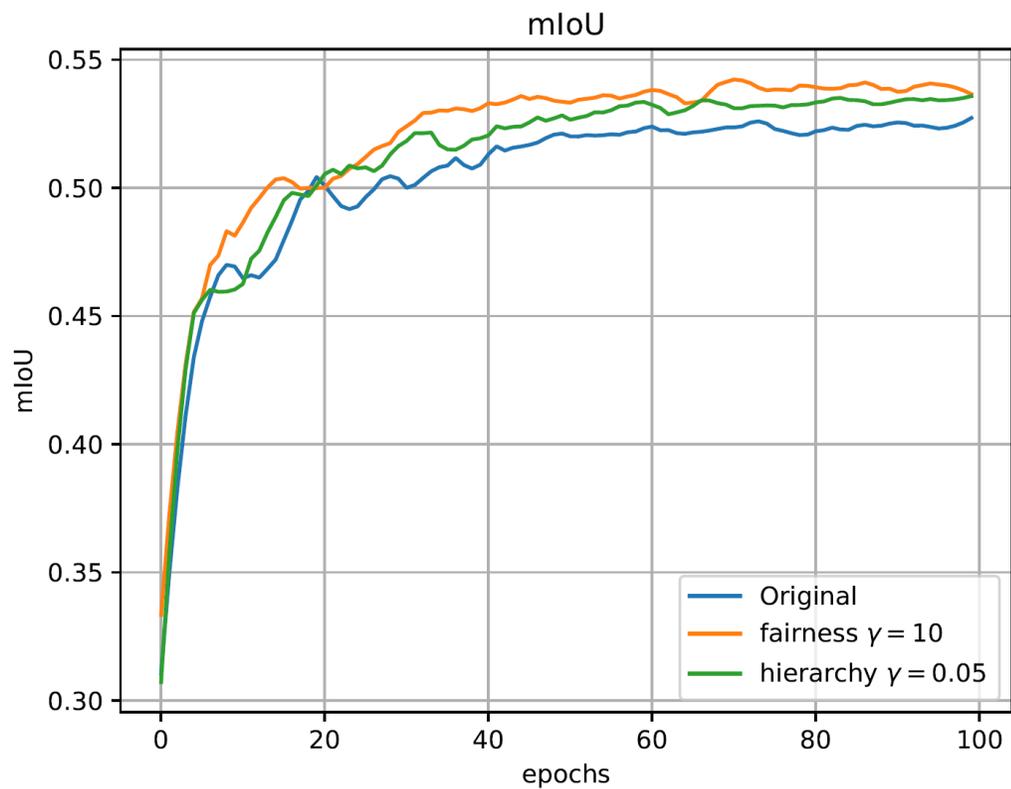
Fairness $\gamma = 10$



Hierarchical $\gamma = 0.05$

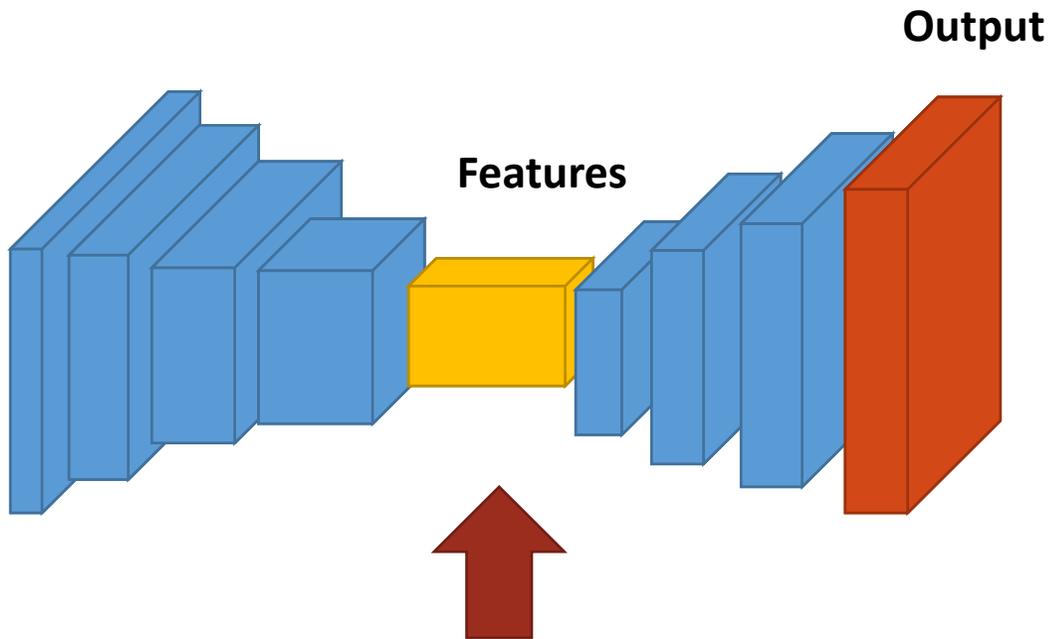
Classes			
unlabeled	other-vehicle	parking	vegetation
car	person	sidewalk	trunk
bicycle	bicyclist	other-ground	terrain
motorcycle	motorcyclist	building	pole
truck	road	fence	traffic-sign

Conclusions



- **Faster** in convergence time and better in terms of **mIoU**.
- Better results in **macro-classes** classification.
- Better **balancement** of classes.

Future works



- Focus on **Feature level** regularization, rather than on **Output level**.
- For methods generalization, **change:**
 - **Dataset**
 - **Architecture**
 - **Task**



Thank you!